Polaris

Enabling Transaction Priority in Optimistic Concurrency Control

Rahul Kushwaha, Jan 28, 2024

Polaris: Introduction

- Optimistic Concurrency Control protocol which supports multiple levels of priority.
- Transactions with same priority are fully optimistic.
- Prioritization is accomplished via Reservation.
- Benefits
	- Significantly lower p999 tail latency.
	- Higher throughput for high contention workloads.

• 3 Phases of a transaction: Read, Validation, and Write.

Img Src: [1]

- Read: Concurrent, multiple transactions can be executing in parallel in this phase.
	- Any mutation to the data is kept within the context of txn.
	- Read your own writes.
- Validation: Serial, global critical section.
- Write: Serial, global critical section.

Silo

- In-Memory database designed for modern multicore machines(high processor count & lots of main memory).
- Is a Serializable Database.
- Uses a variant of Optimistic Concurrency Control.
- Avoids centralized contention.
	- Example: Requires writes to shared memory only during commit phase.

Silo Details

- Is based on time periods called epochs.
- Epochs form serialization points.
- A dedicated thread is responsible for perodically incrementing the epoch number(Global).
- All worker threads access Global Epoch Number during commit.

Silo

- Per-Record field, TransactionID (TID)
	- Data Version
	- Latch

Polaris TID

• Each record has a TID field.

Algorithm 1: Record Access Protocol

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Data: transaction priority $tx.\text{prio}$, record r, read-set R, write-set W, access type is write 1 do

```
do
 \overline{2}tid = r.tid // atomic load
 3
        while tid. \text{latch} == \text{LOCKED}\overline{4}new tid, is reserved = try_reserve(tid, tx.prio, is write)
 5
       r local copy = r \text{.} \text{copy}()6
 7 while !compare_and_swap(r.tid, tid, new tid)
 \mathbf{s} R.add(\mathbf{r}, is reserved, new tid)
 9 if is write then
        W.add(r)10
11 return r local copy
```
Algorithm 2: Reservation Protocol

- Goal: Low-priority txn should not abort a high-priority txn.
- Example:
	- Two txns, [A -> high priority, B -> low priority]
	- If A has read the record but not committed, B should not be able to write to it, as that will cause A to abort.
	- If B has read the record but not committed, A must be able to ignore B and proceed to read/write/commit.

Algorithm 2: Reservation Protocol

Algorithm 2: Reservation Protocol

Data: transaction priority $tx. prio$, a copy of record TID tid , access type is write 1 function try_reserve(tid, tx.prio, is write):

```
new_tid = tid
\boldsymbol{2}if tid.prio == tx.prio then
3
         /* reserve with same-priority transactions
         new tid.ref cnt++
4
         is reserved = true
5
      else if tid. prio < tx. prio then
6
          /* preempt from low-priority transactions
         new tid.prio = tx.prio
7
         new tid.ref cnt = 18
         is reserved = true
9
      else
10
         /* reserved by high-priority transactions
         if is write then
11
             ABORT()
12
         is reserved = false
13
      return new_tid, is_reserved
14
```
Algorithm 3: Commit Protocol(Pt-1)

Algorithm 3: Commit Protocol Data: transaction priority $tx. prio$, read-set R , write-set W 1 for r in sorted(W) do do $\overline{2}$ $tid = r.tid //$ atomic load 3 if $tid. prio > tx. prio$ or $tid. latch == LOCKED$ then 4 ABORT() 5 $locked$ tid = tid 6 locked tid.latch = LOCKED 7 while !compare_and_swap(r.tid, tid, locked tid) 8 **9 for** r, is reserved, tid in R do curr $tid = r.tid //$ atomic load 10 if curr tid.latch == $LOCALED$ and r not in W then 11 **ABORT()** // locked by another transaction 12 if curr_tid.data_ver != tid.data_ver then 13 **ABORT()** // data has been updated 14 /* validation pass; transaction can commit

Algorithm 3: Commit Protocol(Pt-2)

```
15 new data ver = W.max_data_ver() + 1
16 for r in W do
      r.install_write()
17
      tid = r.tid // atomic load
18
      new tid = cleanup_write(tid, new data ver)
19
      r.tid = new tid // atomic store20
21 for r, is reserved, old tid in R do
      if r not in W and is reserved then
22
          do
23
             tid = r.tid // atomic load
24
             new_tid = cleanup_read(tid, tx.prio, old_tid.prio_ver)
25
             if new tid == tid then
26
                 break // no cleanup needed
27
          while !compare_and_swap(r.tid, tid, new tid)
28
```
Algorithm 4: Write CleanUp

12 function cleanup_write(tid, new_data_ver):

- new_tid.data_ver = new_data_ver 13
- new_tid.latch = UNLOCKED 14

$$
15 \quad | \quad new_tid. \text{prio} = 0
$$

$$
16
$$
 new_tid.prio_ver = tid.prio_ver + 1

$$
17 \quad | \quad new_tid.ref_cnt = 0
$$

$$
18 \quad \boxed{\quad \textbf{return } new_tid}
$$

Algorithm 4: Read CleanUp

```
1 function cleanup_read(tid, tx.prio, prio_ver):
```


Priority Assignment

$$
p = \begin{cases} p_0, & \text{if abort_cnt} < t \\ p_0 + \lfloor (abort_cnt - t)/s \rfloor, & \text{otherwise} \end{cases}
$$

Results: YCSB Varying number of high priority & low priority txns

Results: YCSB

Fig. 3. Throughput and p999 tail latency over a spectrum of thread numbers; latency distribution in the cases of 16 and 64 threads (YCSB-A, $r = 50\%$, $w = 50\%$, $\theta = 0.99$).

Results: YCSB

Results: TPC-C [High Contention]

Results: TPC-C [Low Contention]

Thank You!!

References

- [1]H.T.Kung and JohnT.Robinson.1981. On Optimistic Methods for Concurrency Control. ACMTrans.DatabaseSyst.6, 2(jun1981),213–226. <https://doi.org/10.1145/319566.319567>
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